

Kosuke Shikata

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Information

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- Https://scholar.google.com/citations?user=jZ6qQ-cAAAJ
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- https://www.linkedin.com/in/cicodeer/
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Research interests

- Physical human-robot-environment interactions
- Control and utilization of vibration in mechanical systems
- Teleoperation and telerobotics
- Haptic sharing and Human motion information
- Functional electrical stimulation and biosignals-based robotics

Education

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Experiences

Research intern

Wrocław University of Science and Technology

– Towards collaborative research with the team led by Prof. Krzysztof Szabat

– Local stay in Wroclaw Poland for one month (Jan. 2024 – Feb. 2024)

Jan. 2024 – Wrocław, Poland

• Student member Fourth Editorial Subcommittee of the Institute of Electrical Engineers of Japan (IEEJ)	Apr. 2022 – Present Tokyo
– Interviewing with laboratories/companies and writing articles for the Journal of IEEJ (in	n Japanese) 🚳 🏍 🚳
• Teaching assistant Keio University	<i>Oct. 2022 – Jan. 2024</i> Yokohama
– Assistant for the lecture "Electromechanical Energy Conversion" given by Prof. Seiichi	ro Katsura
• Tutor Keio University	<i>Nov. 2022 – Sep. 2023</i> Yokohama
 Support for the study and research of the international student participating in the Japan-Europe Master on Advanced Robotics (JEMARO) project 	
• Secretary International Symposium on Applied Abstraction and Integrated Design (AAID)	Mar. 2023 Yokohama
 Engaged in planning, preparation, and operation of the academic symposium Third International Symposium on Applied Abstraction and Integrated Design (AAID) 	2023)
• Summer intern Mitsubishi Electric Corporation	Aug. 2022 Itami, Hyogo
– Experienced the development of railway vehicle brakes in the transportation systems g	roup
• Butcher shop salesperson/cashier New-Quick CO.LTD.	<i>May. 2018 – Aug. 2022</i> Yokohama
– Acquired customer service and interpersonal skills at the local store	
Grants/Scholarships	
• Research Fellowships for Young Scientists, DC1 Japan Society for the Promotion of Science (JSPS)	Apr. 2024 –
– Title: Establishment of Spatiotemporal Haptic Extension by Integrated Design of Hun	nan, Robot, and ICT
• Scholarships for Doctoral Programs in Graduate Schools Amano Institute of Technology	Oct. 2023 –
– Title: Engineering of Interaction in Robot Manipulations	
• JST-SPRING Japan Science and Technology Agency (JST)	Oct. 2023 – Mar. 2024 JPMJSP2123
 As an adopter of the Keio-SPRING project Title: Constituent Unit in Motion Control and Information Communication for Multil 	ateral Haptic Sharing
• Fujiwara Scholarship Keio University	Dec. 2023

Last updated: June 14, 2024

- Koizumi fund travel assistance for graduate students Keio University
- Bakheet scholarship Keio Unversity
- Master's program research grant Keio Leading-edge Laboratory of Science and Technology (KLL)

Publications/Achievements

Journal

- 1. Kosuke Shikata and Seiichiro Katsura, "Wave dynamics intrinsic in symmetric four-channel bilateral teleoperation: Mutual impedance-based motion control," Mechatronics, Vol. 102 p. 103209, October, 2024. 🗐
- 2. Kosuke Shikata and Seiichiro Katsura, "Modal Space Control of Bilateral System with Elasticity for Stable Contact Motion," IEEJ Journal of Industry Applications, Vol. 12, No. 2, pp. 131–144, March, 2023.

International conference

- 1. Kosuke Shikata and Seiichiro Katsura, "Hybrid Velocity/Force Filtered Integral-Proportional Control for Damping of Torsional Vibration," 21st International Conference on Power Electronics and Motion Control (IEEE-PEMC2024), Pilsen, Czech Republic, October, 2024. (Accepted)
- 2. Kosuke Shikata and Seiichiro Katsura, "Hierarchical Control for Vibration Suppression Through Decoupling of Traveling/Reflected Waves," 49th Annual Conference of the IEEE Industrial Electronics Society (IECON 2023), Singapore, October, 2023, pp. 1–6.
- 3. Kosuke Shikata and Seiichiro Katsura, "Vibration Suppression Control Tolerant to Inertial Variations Based on Transformation to Traveling/Reflected Wave Basis," SICE Annual Conference 2023, Mie, Japan, September, 2023, pp. 821–826.
- 4. Kosuke Shikata and Seiichiro Katsura, "Mutual Impedance-Based Force/Velocity Transmission Improvement for Bilateral Teleoperation," 22nd World Congress of the International Federation of Automatic Control (IFAC World Congress 2023), Yokohama, Japan, July, 2023, pp. 9992–9997.
- 5. Kosuke Shikata and Seiichiro Katsura, "Disturbance-Observer-Based Admittance Control and Its Application to Safe Contact Regulation," 2023 IEEE/ASME International Conference on Advanced Intelligent Mechatronics (AIM), Seattle, WA, USA, June, 2023, pp. 311–316.
- 6. Kosuke Shikata and Seiichiro Katsura, "Controller Design Considering Intrinsic Wave System for Four-Channel Bilateral Teleoperation," 3rd International Symposium on Applied Abstraction and Integrated Design (AAID2023), Yokohama, Japan, March, 2023, pp. 22–27.
- 7. Kosuke Shikata and Seiichiro Katsura, "Reflected Wave Control for Generating Impact Motion Using a Flexible Manipulator," 48th Annual Conference of the IEEE Industrial Electronics Society (IECON2022), Brussels, Belgium, October, 2022, pp. 1–6.
- 8. Kosuke Shikata and Seiichiro Katsura, "Impact Motion of a Flexible Manipulator Based on Reflected Wave Control," SICE Annual Conference 2022, Kumamoto, Japan, September, 2022, pp. 1265–1269.
- 9. Kosuke Shikata and Seiichiro Katsura, "Vibration Suppression for Bilateral System with Resonance," 8th IEEJ International Workshop on Sensing, Actuation, Motion Control, and Optimization (SAMCON2022), Saitama, Japan, March, 2022, pp. 526–527.

Domestic conference

8 presentations as the first author (in Japanese)

Oct. 2022

Nov. 2023

Apr. 2022 - Sep. 2023

Awards

• Excellent Research Activity Award (Master) Keio University	Mar. 2024
– For the research activity in his master course"	
• Miura Award Japan Society Mechanical Engineers (JSME)	Mar. 2024
– For the research activity in his master course"	
• Academic Encouragement Award Society of Instrument and Control Engineers (SICE)	Mar. 2024
 For the research titled "Identification of Distributed/Lumped-Parameter Coupling Model Toward Wave Control" 	
• Excellent Presentation Award in the 66th Japan Joint Automatic Control Conference Society of Instrument and Control Engineers (SICE)	Oct. 2023
 For the presentation titled "Identification of Distributed/Lumped-Parameter Coupling Model Toward Wave Control" 	
• Finalist in the SICE Annual Conference Young Author's Award Society of Instrument and Control Engineers (SICE)	Sep. 2023
– For the paper and presentation at the SICE Annual Conference 2023	
• IEEJ Industry Applications Society Excellent Presentation Award Institute of Electrical Engineers of Japan (IEEJ)	Jan. 2023
– For the presentation titled "Interaction Control of Flexible Structures based on Wave Model"	
 Encouragement Award in Electrical Engineering Tokyo Branch, Institute of Electrical Engineers of Japan (IEEJ) For academic diligence and results as a student member of IEEJ 	Mar. 2022
 Excellent Presentation Award Tokyo Branch, Institute of Electrical Engineers of Japan (IEEJ) 	Aug. 2021
– For the presentation at the 11th Student Research Presentation Conference	

Skills

- **Programming and Simulation** C/C++, Python, MATLAB
- Hardware Development Mechanical design for robotics, Fusion 360 (CAD), 3D Printing, Electronic circuit design, KiCad, FPGA
- Visualization and Design LAT_EX, gnuplot, Adobe Illustrator, Microsoft PowerPoint

Professional associations

- Institute of Electrical and Electronics Engineers (IEEE) – Industrial Electronics Society (IES)
- Institute of Electrical Engineers of Japan (IEEJ)
- Japan Society of Mechanical Engineers (JSME)
- Society of Instrument and Control Engineers (SICE)

Languages

Japanese	Mothertongue	
English	Intermediate	Basic conversational ability

Interests

• Travel

• Geography

• Watching baseball

• Photograph

• Design

• Playing soft tennis